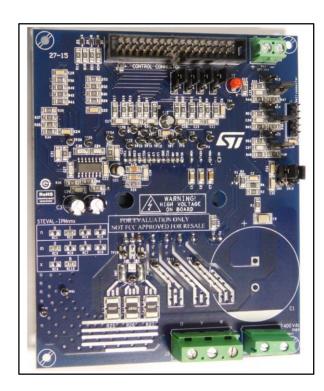


STEVAL-IPM10B

Motor control power board based on the SLLIMM™ 2nd series of IGBT IPMs

Data brief



Features

- Input voltage: 125 400 V_{DC}
 Nominal power: up to 1200 W
- Input auxiliary voltage: up to 20 V DC
- Single- or three- shunt resistors for current sensing (with sensing network)
- Two options for current sensing: dedicated op-amps or through MCU
- Overcurrent hardware protection
- IPM temperature monitoring and protection
- Hall sensor or encoder input
- Uses the STGIB10CH60TS-L IGBT intelligent power module from the 2nd series of SLLIMM™ IPMs
- Motor control connector (32-pin) to interface with ST MCU boards

- Universal conception for further evaluation with breadboard and testing pins
- Very compact size
- RoHS compliant

Description

The STEVAL-IPM10B is a compact motor drive power board based on the SLLIMM™ (small low-loss intelligent molded module) 2nd series module STGIB10CH60TS-L. It provides an affordable, easy-to-use solution for driving high power motors for a wide range of applications such as white goods, air conditioners, compressors, power fans, high-end power tools, and generally 3-phase inverters for motor drives. The IPM itself consists of short-circuit rugged IGBTs and a wide range of features including undervoltage lockout, smart shutdown, temperature sensing and NTC inside, and overcurrent protection.

The main characteristics of this evaluation board are its small size, minimal BOM and high efficiency. It consists of an interface circuit (BUS and V_{CC} connectors), bootstrap capacitors, snubber capacitor, hardware short-circuit protection, fault event signal, temperature monitoring. In order to increase its flexibility, it was designed to work in single or three-shunt configuration and with double current sensing options such as three dedicated op-amps on-board, or op-amps embedded on MCU. Hall/Encoder part completes the circuit.

Thanks to these advanced characteristics, the system has been specifically designed to achieve accurate and fast conditioning of the current feedback, matching the typical requirements for field-oriented control (FOC).

The STEVAL-IPM10B is compatible with ST's STM32-based control board, providing a complete platform for motor control.

Schematic diagram STEVAL-IPM10B

1 Schematic diagram

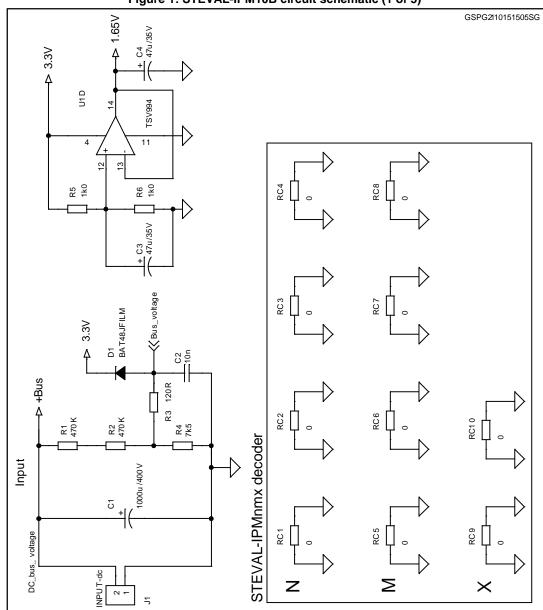


Figure 1: STEVAL-IPM10B circuit schematic (1 of 5)

STEVAL-IPM10B Schematic diagram

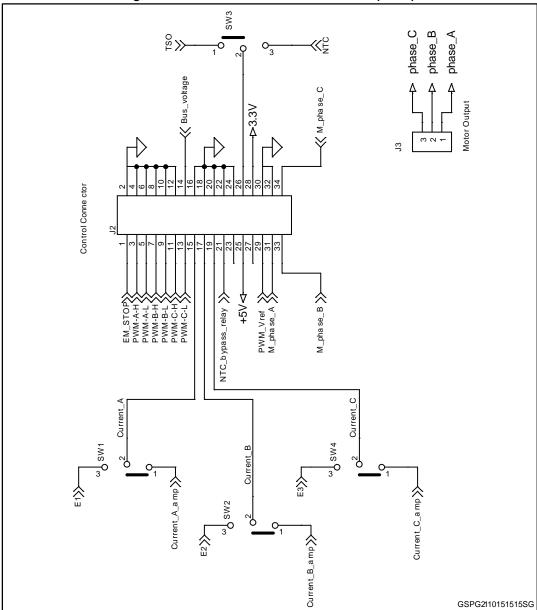


Figure 2: STEVAL-IPM10B circuit schematic (2 of 5)

Schematic diagram STEVAL-IPM10B

Figure 3: STEVAL-IPM10B circuit schematic (3 of 5) GSPG2110151530SG Current_B_amp R36 * 75 3.3√ U1C TSV994 10 R34 2k1 R39 2k1 10 C26 100p 1k0 1k0 1.65√ 4 R35 R37 330p 330p R31 ₹ 3.3 * R41 ***** ₹ 3.3√ U1A TSV994 C21 +/ U1B TSV994 R29 2k1 R33 R43 R38 2k1 10n 100p \$ 198 \$ 198 1k0 1k0 1.65√ 4 R40

R42

R30

R32

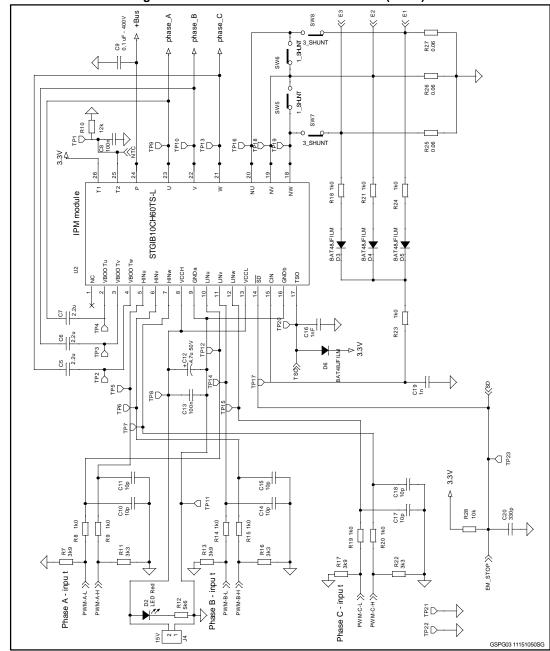


Figure 4: STEVAL-IPM10B circuit schematic (4 of 5)

GSPG2110151550SG M_phase_A M_phase_B M_phase_C SW15 R52 4k7 SW14 R51 4k7 SW13 R50 4K7 R46 4k7 C37 10p R45 4k7 C36 10p R44 4k7 C35 Hall/Encoder 2k4 2k4 2k4 SW12 SW11 C34 100n 6MS 0 s 0 SW16 <u>-</u>1 Encoder/Hall C32 100n C33 H1/A+ H2/B+ H3/Z+ + 3.3/5V GND ±5V △ 3.3∨ △-

Figure 5: STEVAL-IPM10B circuit schematic (5 of 5)

STEVAL-IPM10B Revision history

2 Revision history

Table 1: Document revision history

Date	Version	Changes
12-Nov-2015	1	Initial release.
24-Feb-2016	2	Updated: Figure 1: "STEVAL-IPM10B circuit schematic (1 of 5)" and Figure 3: "STEVAL-IPM10B circuit schematic (3 of 5)".

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